

# Bayesian Decision Theory

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Computer Science- Pattern Recognition

Prof. Dr. Dhahir A. Abdullah

## Case 2: $\Sigma_i = \Sigma$

- Covariance matrices for all of the classes are identical,
- But covariance matrices are arbitrary.

## Case 2: $\Sigma_i = \Sigma$

$$g_i(\mathbf{x}) = -\frac{1}{2}(\mathbf{x} - \mu_i)^t \sum_i^{-1} (\mathbf{x} - \mu_i) - \frac{d}{2} \ln 2\pi - \frac{1}{2} \ln |\Sigma_i| + \ln P(\omega_i)$$

$\frac{d}{2} \ln 2\pi$  and  $\frac{1}{2} \ln |\Sigma_i|$  are independent of  $i$ .

So,

$$g_i(\mathbf{x}) = -\frac{1}{2}(\mathbf{x} - \mu_i)^t \sum_i^{-1} (\mathbf{x} - \mu_i) + \ln P(\omega_i)$$

## Case 2: $\Sigma_i = \Sigma$

Discriminant functions are

$$g_i(\mathbf{x}) = \mathbf{w}_i^T \mathbf{x} + w_{i0} \quad (\text{linear discriminant})$$

where

$$\mathbf{w}_i = \Sigma^{-1} \mu_i$$

$$w_{i0} = -\frac{1}{2} \mu_i^T \Sigma^{-1} \mu_i + \ln P(w_i).$$

## Case 2: $\Sigma_i = \Sigma$

Decision boundaries can be written as

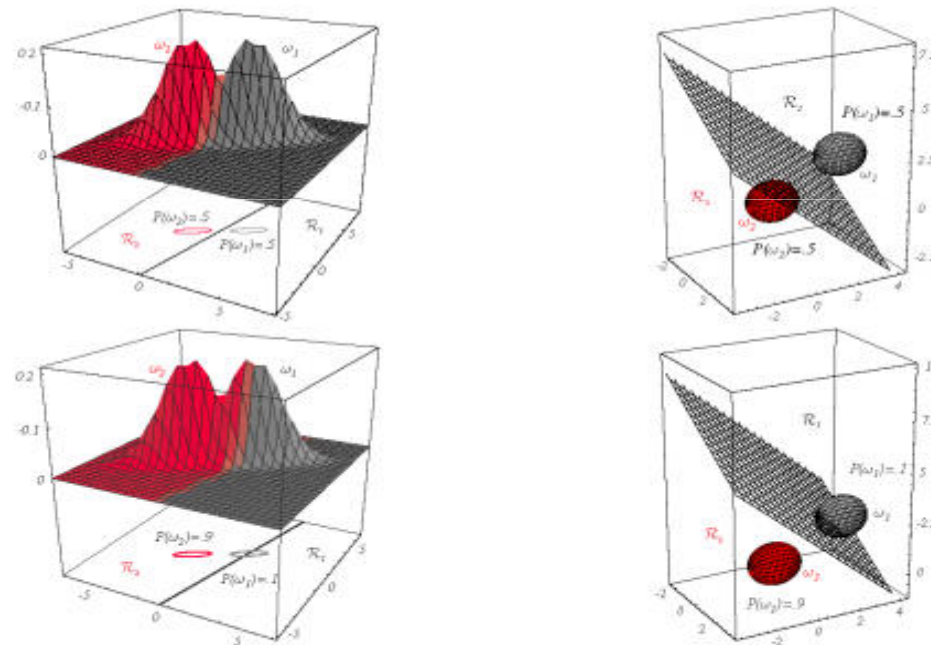
$$\mathbf{w}^T(\mathbf{x} - \mathbf{x}_0) = 0$$

where

$$\begin{aligned}\mathbf{w} &= \Sigma^{-1}(\mu_i - \mu_j) \\ \mathbf{x}_0 &= \frac{1}{2}(\mu_i + \mu_j) - \frac{\ln(P(w_i)/P(w_j))}{(\mu_i - \mu_j)^T \Sigma^{-1}(\mu_i - \mu_j)}(\mu_i - \mu_j).\end{aligned}$$

Hyperplane passes through  $\mathbf{x}_0$  but is not necessarily orthogonal to the line between the means.

## Case 2: $\Sigma_i = \Sigma$



**Figure 6:** Probability densities with equal but asymmetric Gaussian distributions. The decision hyperplanes are not necessarily perpendicular to the line connecting the means.

## Case 3: $\Sigma_i = \text{arbitrary}$

- Covariance matrices are different for each category.

### Case 3: $\Sigma_i = \text{arbitrary}$

$$g_i(x) = -\frac{1}{2}(x - \mu_i)^t \sum_i^{-1} (x - \mu_i) - \frac{d}{2} \ln 2\pi - \frac{1}{2} \ln |\Sigma_i| + \ln P(\omega_i)$$

only  $\frac{d}{2} \ln 2\pi$  is independent of  $i$ .

So,

$$g_i(x) = -\frac{1}{2}(x - \mu_i)^t \sum_i^{-1} (x - \mu_i) - \frac{1}{2} \ln |\Sigma_i| + \ln P(\omega_i)$$

## Case 3: $\Sigma_i = \text{arbitrary}$

Discriminant functions are

$$g_i(\mathbf{x}) = \mathbf{x}^T \mathbf{W}_i \mathbf{x} + \mathbf{w}_i^T \mathbf{x} + w_{i0} \quad (\text{quadratic discriminant})$$

where

$$\mathbf{W}_i = -\frac{1}{2} \Sigma_i^{-1}$$

$$\mathbf{w}_i = \Sigma_i^{-1} \boldsymbol{\mu}_i$$

$$w_{i0} = -\frac{1}{2} \boldsymbol{\mu}_i^T \Sigma_i^{-1} \boldsymbol{\mu}_i - \frac{1}{2} \ln |\Sigma_i| + \ln P(w_i).$$

Decision boundaries are hyperquadrics.

## Case 3: $\Sigma_i = \text{arbitrary}$

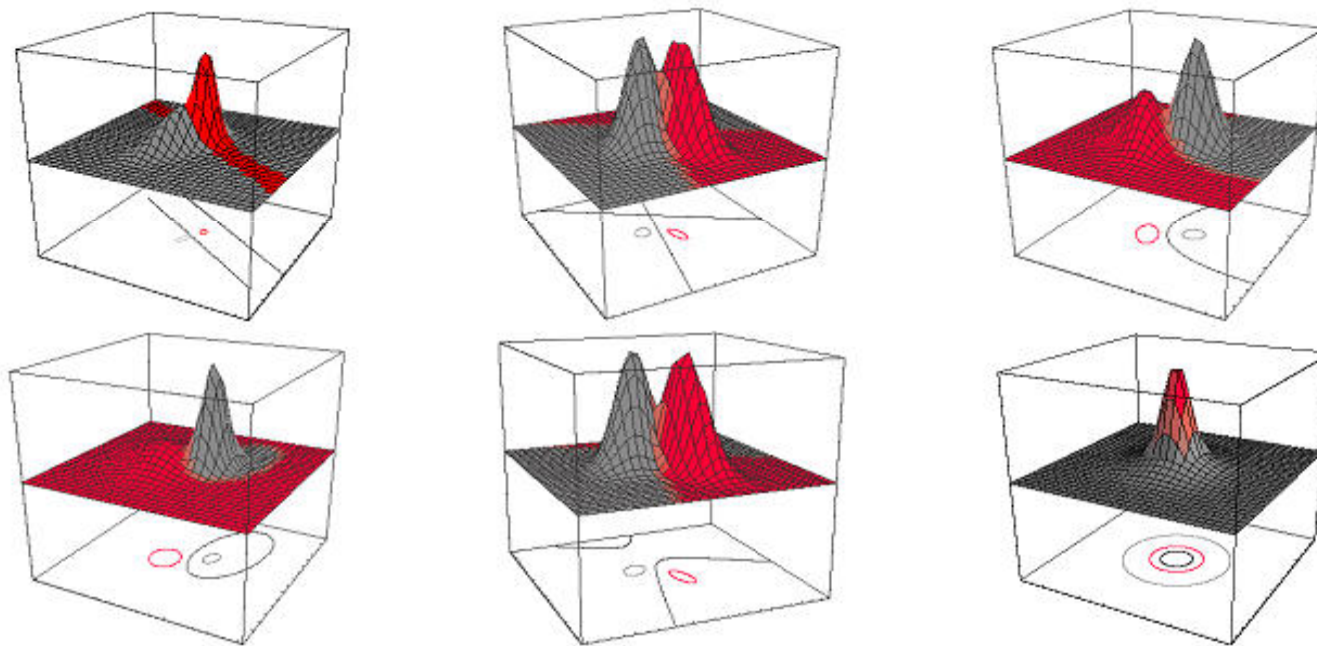
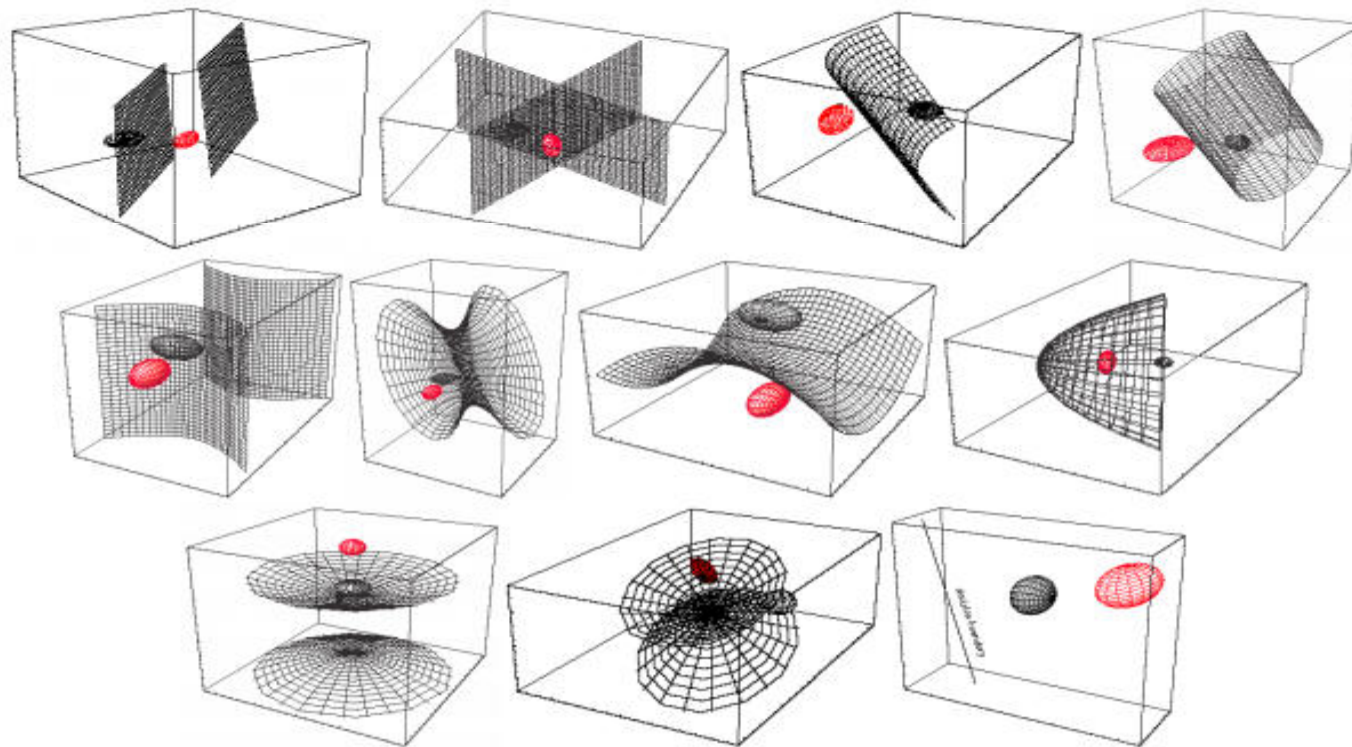


Figure 7: Arbitrary Gaussian distributions lead to Bayes decision boundaries that are general hyperquadrics.

## Case 3: $\Sigma_i = \text{arbitrary}$



**Figure 8:** Arbitrary Gaussian distributions lead to Bayes decision boundaries that are general hyperquadrics.

## EXAMPLE:

Consider a two-category classification problem  
with two-dimensional feature vector  $X = (x_1, x_2)^t$ .

The two categories are  $\omega_1$  and  $\omega_2$ .

$$p(X|\omega_1) \sim N\left(\begin{bmatrix} -1 \\ 1 \end{bmatrix}, \Sigma_1\right),$$

$$p(X|\omega_2) \sim N\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \Sigma_2\right), \quad \Sigma_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \Sigma_2 = \begin{bmatrix} 2 & 2 \\ 2 & 3 \end{bmatrix}.$$

$$P(\omega_1) = P(\omega_2) = \frac{1}{2}$$

## EXAMPLE (cont.):

Calculate the Bayes decision boundary.

## EXAMPLE (cont.):

Find the **discriminant function for the first class**.

$$\begin{aligned} g_1(x) &= -\ln(2\pi) - \frac{1}{2} \ln |\Sigma_1| - \frac{1}{2} (\bar{x} - \bar{\mu}_1)^t \Sigma_1^{-1} (\bar{x} - \bar{\mu}_1) \\ &= -\ln(2\pi) - \frac{1}{2} \ln |\Sigma_1| - \frac{1}{2} \begin{bmatrix} x_1 - \mu_{11} & x_2 - \mu_{12} \end{bmatrix} \Sigma_1^{-1} \begin{bmatrix} x_1 - \mu_{11} \\ x_2 - \mu_{12} \end{bmatrix} \end{aligned}$$

## EXAMPLE (cont.):

Find the **discriminant function for the first class**.

$$\begin{aligned} & -\ln(2\pi) - \frac{1}{2} \ln |\Sigma_1| - \frac{1}{2} \begin{bmatrix} x_1 - \mu_{11} & x_2 - \mu_{12} \end{bmatrix} \Sigma_1^{-1} \begin{bmatrix} x_1 - \mu_{11} \\ x_2 - \mu_{12} \end{bmatrix} = \\ & = -\ln(2\pi) - \frac{1}{2} \ln 1 - \frac{1}{2} \begin{bmatrix} x_1 + 1 & x_2 - 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 + 1 \\ x_2 - 1 \end{bmatrix} \\ & = -\ln(2\pi) - \frac{1}{2} \left( (x_1 + 1)^2 + (x_2 - 1)^2 \right) \\ & = -\ln(2\pi) - \frac{1}{2} \left( x_1^2 + 2x_1 + 1 + x_2^2 - 2x_2 + 1 \right) \end{aligned}$$

## EXAMPLE (cont.):

Similarly, find the **discriminant function for the second class**.

$$\begin{aligned} g_2(x) &= -\ln(2\pi) - \frac{1}{2} \ln |\Sigma_2| - \frac{1}{2} (\bar{x} - \bar{\mu}_2)^t \Sigma_2^{-1} (\bar{x} - \bar{\mu}_2) \\ &= -\ln(2\pi) - \frac{1}{2} \ln |\Sigma_2| - \frac{1}{2} [x_1 - \mu_{21} \quad x_2 - \mu_{22}] \Sigma_2^{-1} \begin{bmatrix} x_1 - \mu_{21} \\ x_2 - \mu_{22} \end{bmatrix} \\ &= -\ln(2\pi) - \frac{1}{2} \ln 2 - \frac{1}{2} [x_1 - 1 \quad x_2] \frac{1}{2} \begin{bmatrix} 3 & -2 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x_1 - 1 \\ x_2 \end{bmatrix} \\ &= -\ln(2\pi) - \frac{1}{2} \ln 2 - \frac{1}{4} [3(x_1 - 1) - 2x_2 \quad -2(x_1 - 1) + 2x_2] \begin{bmatrix} x_1 - 1 \\ x_2 \end{bmatrix} \\ &= -\ln(2\pi) - \frac{1}{2} \ln 2 - \frac{1}{4} (3(x_1 - 1)^2 - 2(x_1 - 1)x_2 - 2(x_1 - 1)x_2 + 2x_2^2) \\ &= -\ln(2\pi) - \frac{1}{2} \ln 2 - \frac{1}{4} (3x_1^2 - 6x_1 + 3 - 4x_1x_2 + 4x_2 + 2x_2^2) \end{aligned}$$

## EXAMPLE (cont.):

The **decision boundary**:

$$g(x) = g_1(x) - g_2(x)$$

$$= -\ln(2\pi) - \frac{1}{2}(x_1^2 + 2x_1 + 1 + x_2^2 - 2x_2 + 1) + \ln(2\pi) + \frac{1}{2}\ln 2 - \frac{1}{4}(3x_1^2 - 6x_1 + 3 - 4x_1x_2 + 4x_2 + 2x_2^2)$$

$$= -\frac{1}{2}(x_1^2 + 2x_1 + 1 + x_2^2 - 2x_2 + 1) + \frac{1}{2}\ln 2 + \frac{1}{4}(3x_1^2 - 6x_1 + 3 - 4x_1x_2 + 4x_2 + 2x_2^2)$$

$$= -\frac{1}{2}x_1^2 - x_1 - \frac{1}{2} - \frac{1}{2}x_2^2 + x_2 - \frac{1}{2} + \frac{1}{2}\ln 2 + \frac{3}{4}x_1^2 - \frac{6}{4}x_1 + \frac{3}{4} - x_1x_2 + x_2 + \frac{1}{2}x_2^2$$

$$= -\frac{1}{2}x_1^2 + \frac{3}{4}x_1^2 - x_1 - \frac{6}{4}x_1 - x_1x_2 + x_2 + x_2 + \frac{1}{2}x_2^2 - \frac{1}{2}x_2^2 - \frac{1}{2} - \frac{1}{2} + \frac{3}{4} + \frac{1}{2}\ln 2$$

$$= \frac{1}{4}x_1^2 - \frac{10}{4}x_1 - x_1x_2 + 2x_2 - \frac{1}{4} + \frac{1}{2}\ln 2$$

## EXAMPLE (cont.):

The decision boundary:

$$\begin{aligned}g(x) = g_1(x) - g_2(x) &= \frac{1}{4}x_1^2 - \frac{10}{4}x_1 - x_1x_2 + 2x_2 - \frac{1}{4} + \frac{1}{2}\ln 2 \\&= x_1^2 - 10x_1 - 4x_1x_2 + 8x_2 - 1 + 2\ln 2\end{aligned}$$

## EXAMPLE (cont.):

Using MATLAB we can draw the decision boundary:

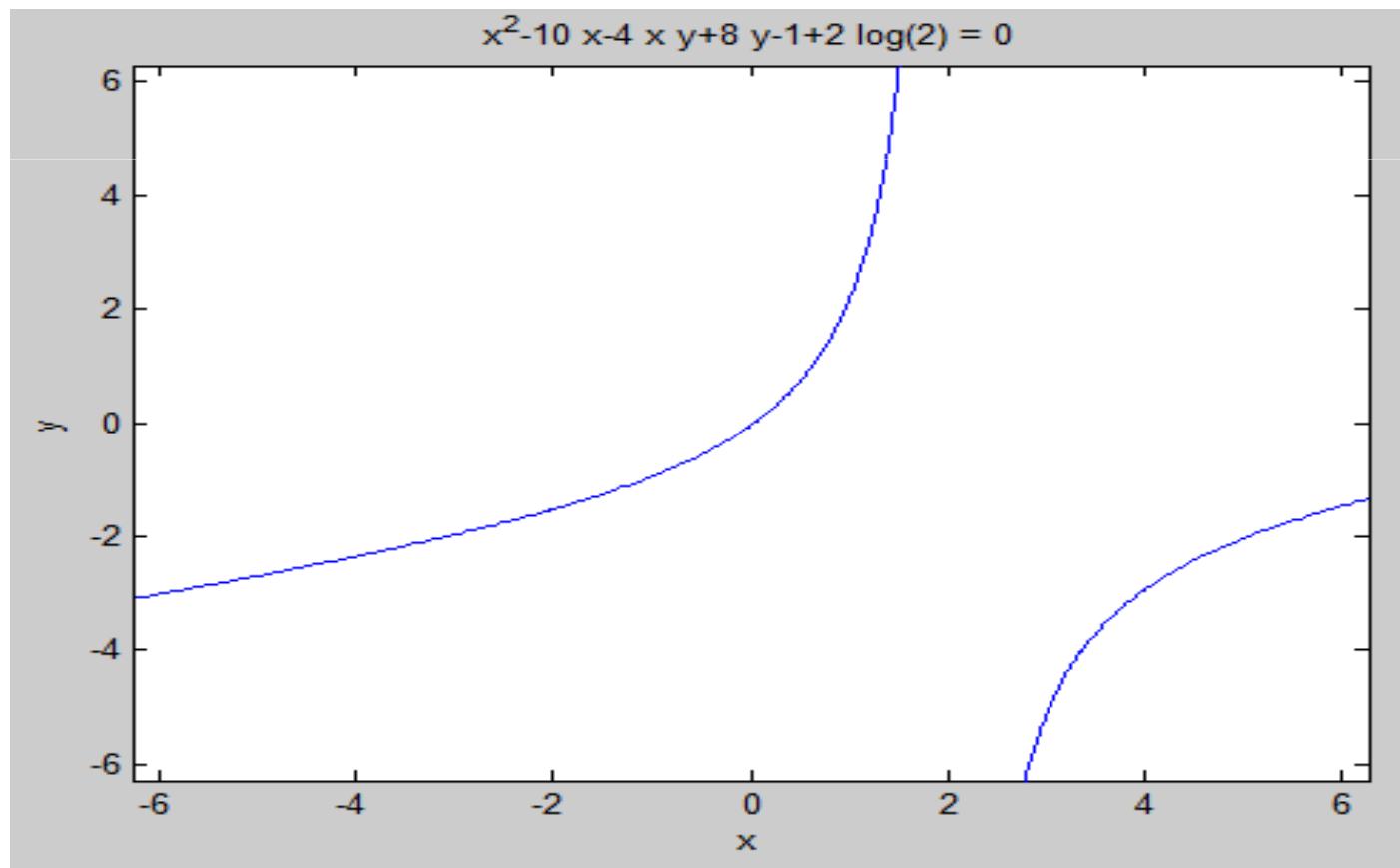
$$g(x) = x_1^2 - 10x_1 - 4x_1x_2 + 8x_2 - 1 + 2\ln 2$$

(to draw the decision boundary in MATLAB)

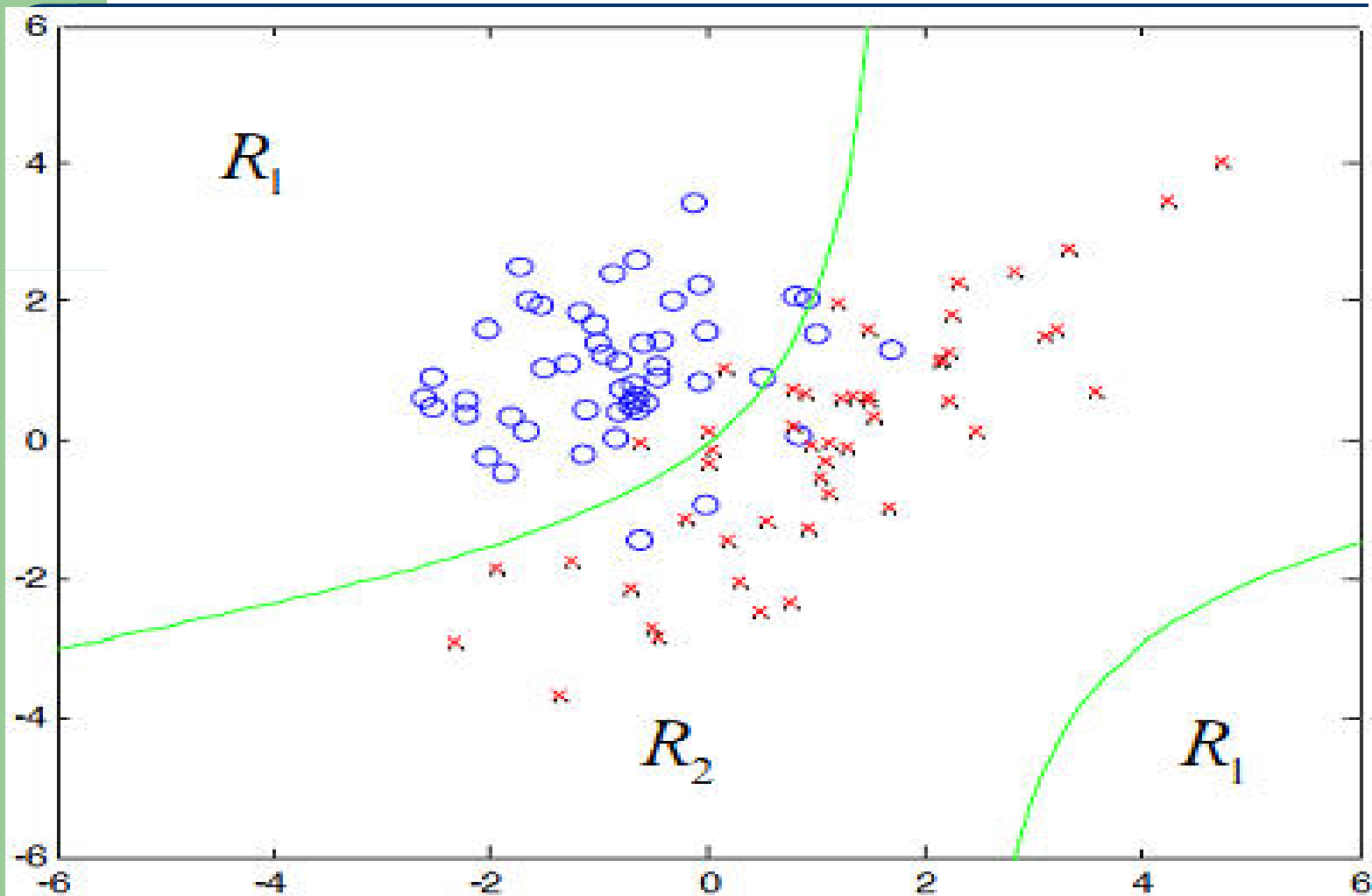
```
>> s = 'x^2-10*x-4*x*y+8*y-1+2*log(2)';  
>> ezplot(s)
```

## EXAMPLE (cont.):

Using MATLAB we can draw the decision boundary:



## EXAMPLE (cont.):



# Error Probabilities and Integrals

For the two-category case

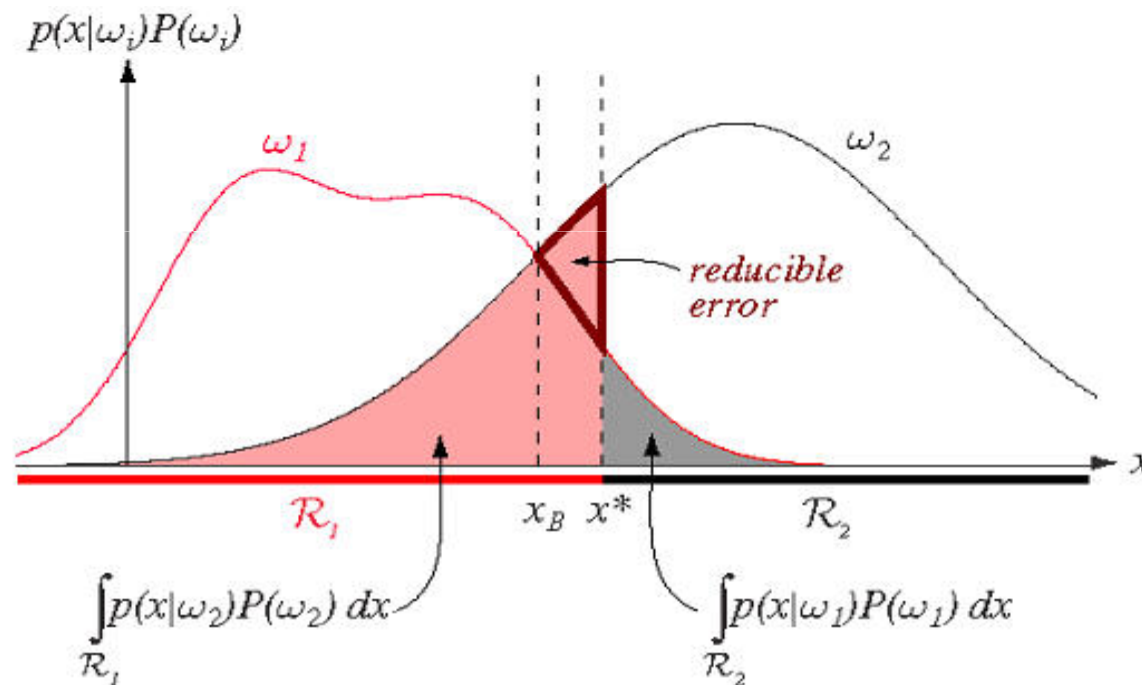
$$\begin{aligned} P(\text{error}) &= P(\mathbf{x} \in \mathcal{R}_2, w_1) + P(\mathbf{x} \in \mathcal{R}_1, w_2) \\ &= P(\mathbf{x} \in \mathcal{R}_2 | w_1) P(w_1) + P(\mathbf{x} \in \mathcal{R}_1 | w_2) P(w_2) \\ &= \int_{\mathcal{R}_2} p(\mathbf{x} | w_1) P(w_1) d\mathbf{x} + \int_{\mathcal{R}_1} p(\mathbf{x} | w_2) P(w_2) d\mathbf{x}. \end{aligned}$$

# Error Probabilities and Integrals

For the multcategory case

$$\begin{aligned} P(\text{error}) &= 1 - P(\text{correct}) \\ &= 1 - \sum_{i=1}^c P(\mathbf{x} \in \mathcal{R}_i, w_i) \\ &= 1 - \sum_{i=1}^c P(\mathbf{x} \in \mathcal{R}_i | w_i) P(w_i) \\ &= 1 - \sum_{i=1}^c \int_{\mathcal{R}_i} p(\mathbf{x} | w_i) P(w_i) d\mathbf{x}. \end{aligned}$$

# Error Probabilities and Integrals



**Figure 9:** Components of the probability of error for equal priors and the non-optimal decision point  $x^*$ . The optimal point  $x_B$  minimizes the total shaded area and gives the Bayes error rate.

# Receiver Operating Characteristics

- Another measure of distance between two Gaussian distributions.
- found a great use in medicine, radar detection and other fields.

# Receiver Operating Characteristics

- ▶ Consider the two-category case and define
  - ▶  $w_1$ : target is present,
  - ▶  $w_2$ : target is not present.

Table 1: *Confusion matrix.*

|      |       | Assigned          |                   |
|------|-------|-------------------|-------------------|
|      |       | $w_1$             | $w_2$             |
| True | $w_1$ | correct detection | mis-detection     |
|      | $w_2$ | false alarm       | correct rejection |

- ▶ Mis-detection is also called false negative or Type I error.
- ▶ False alarm is also called false positive or Type II error.

# Receiver Operating Characteristics

- If we use a parameter (e.g., a threshold) in our decision, the plot of these rates for different values of the parameter is called the *receiver operating characteristic* (ROC) curve.

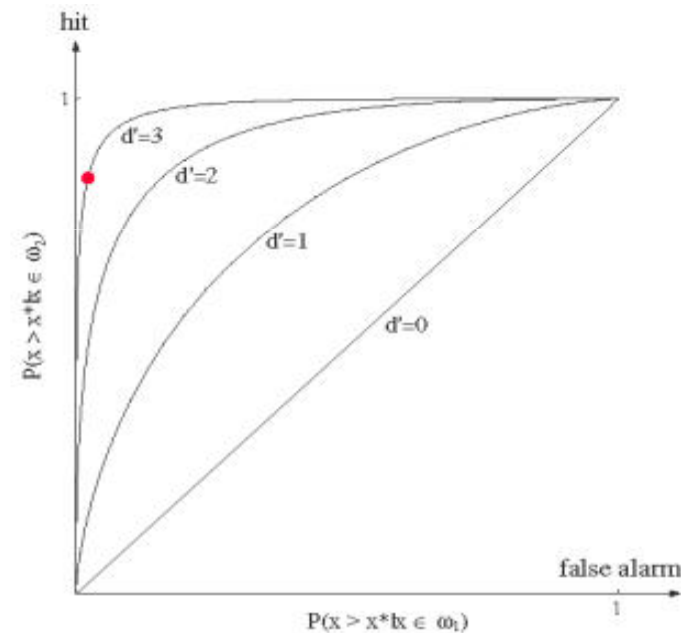


Figure 10: Example receiver operating characteristic (ROC) curves for different settings of the system.

# Receiver Operating Characteristics

Let  $p_i$  be the probability that patient  $i$  will get a positive diagnosis (i.e., the patient is ill) and  $q_i$  be patient  $i$ 's probability of a positive test. The *prevalence*,  $P$ , of the positive diagnosis in the population<sup>2</sup> is theoretically  $P = \text{mean}(p_i)$ . The *level* of the test,  $Q$ , is  $Q = \text{mean}(q_i)$ . We also define  $P' = 1 - P$  and  $Q' = 1 - Q$ .

|                       | Test result |          |      |
|-----------------------|-------------|----------|------|
|                       | Positive    | Negative |      |
| Diagnosis<br>Positive | TP          | FN       | $P$  |
| Negative              | FP          | TN       | $P'$ |
|                       | $Q$         | $Q'$     | 1    |

# Receiver Operating Characteristics

- If both diagnosis and test are positive, it is called a **true positive**. The probability of a TP to occur is estimated by counting the true positives in the sample and divide by the sample size.
- If the diagnosis is positive and the test is negative it is called a **false negative** (FN).
- **False positive** (FP) and **true negative** (TN) are defined similarly.

# Receiver Operating Characteristics

- The values described are used to calculate different measurements of the quality of the test.
- The first one is **sensitivity, SE**, which is **the probability of having a positive test among the patients who have a positive diagnosis.**

$$SE = TP / (TP + FN) = TP / P.$$

# Receiver Operating Characteristics

- **Specificity, SP**, is the probability of having a negative test among the patients who have a negative diagnosis.

$$SP = TN / (FP + TN) = TN / P'.$$

# Receiver Operating Characteristics

- Example:

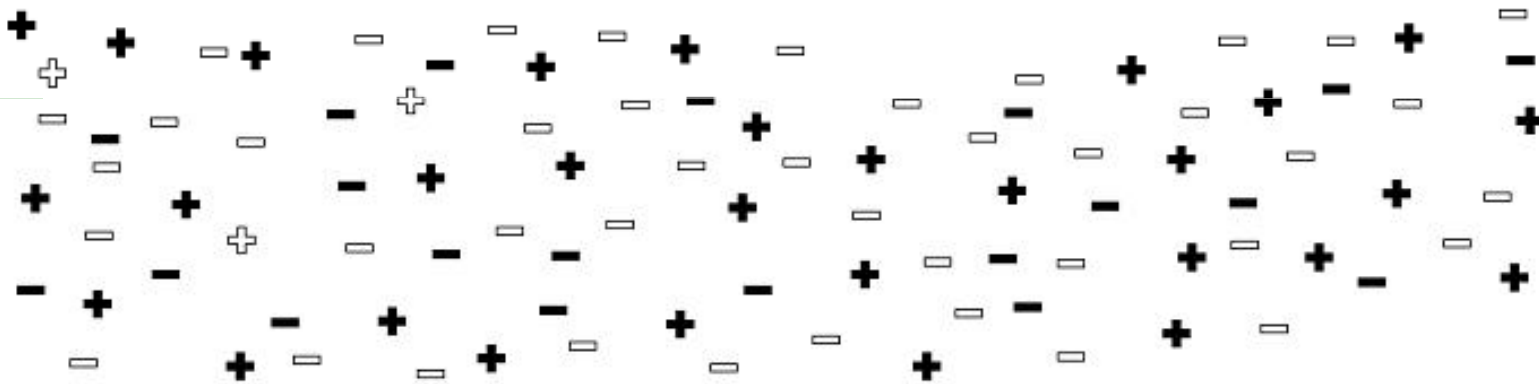


Figure 1.1: A sample population of  $N = 95$  patients. The minus signs denote patients with a negative diagnosis and the plus signs denotes patients with a positive diagnosis. The colour shows the result of a test. White is a negative test and black is a positive test.

# Receiver Operating Characteristics

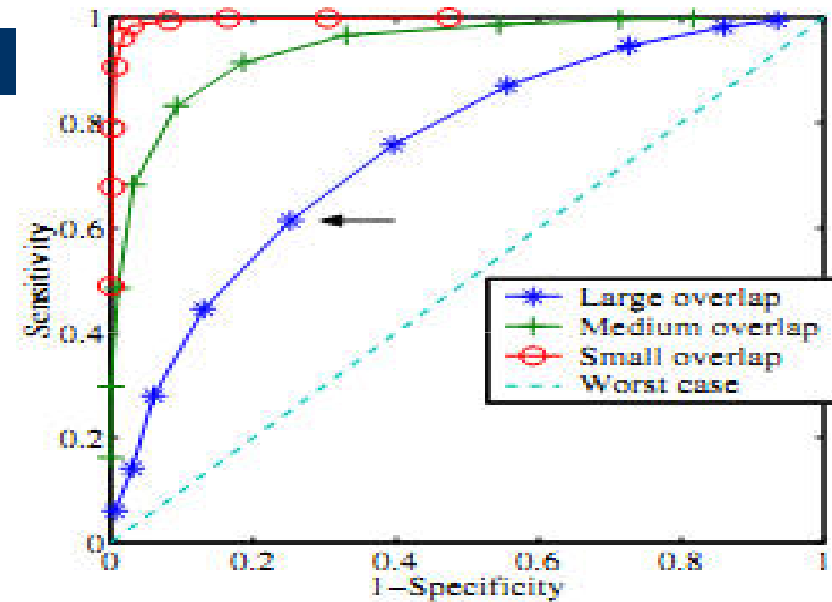
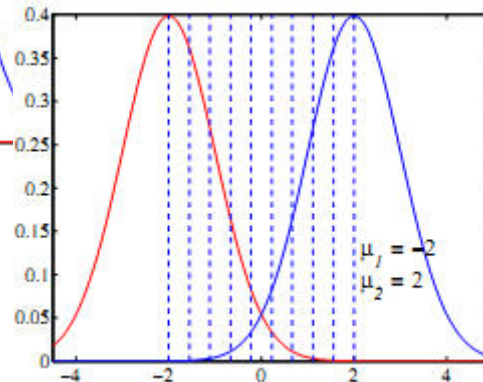
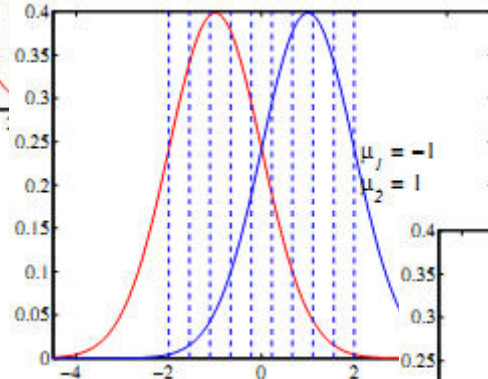
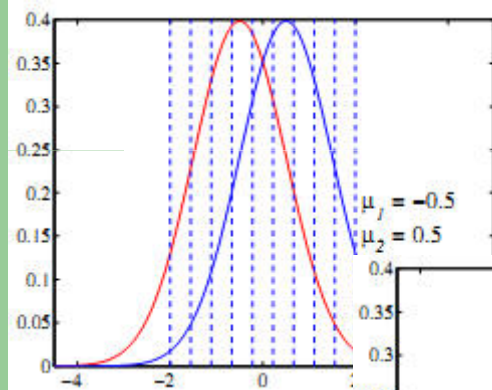
- Example (cont.):

| #Diagnosis | #Test result |          |    |
|------------|--------------|----------|----|
|            | Positive     | Negative |    |
| Positive   | 30           | 3        | 33 |
| Negative   | 20           | 42       | 62 |
|            | 50           | 45       | 95 |

$$\begin{aligned}
 TP &= 30/95 = 0.316(\pm 0.048) & P &= 33/95 = 0.347(\pm 0.049) \\
 FN &= 3/95 = 0.032(\pm 0.018) & Q &= 50/95 = 0.526(\pm 0.051) \\
 FP &= 20/95 = 0.211(\pm 0.042) & SE &= 30/33 = 0.909(\pm 0.050) \\
 TN &= 42/95 = 0.442(\pm 0.051) & SP &= 42/62 = 0.677(\pm 0.059)
 \end{aligned}$$

# Receiver Operating Characteristics

- Overlap in distributions:



## Bayes Decision Theory – Discrete Features

- Assume  $\mathbf{x} = (x_1, \dots, x_d)$  takes only  $m$  discrete values
- Components of  $\mathbf{x}$  are binary or integer valued,  $\mathbf{x}$  can take only one of  $m$  **discrete values**

$$V_1, V_2, \dots, V_m$$

# Bayes Decision Theory – Discrete Features (Decision Strategy)

- *Maximize class posterior using bayes decision rule*

$$P(\omega_i / \underline{x}) = \frac{P(\underline{x} / \omega_i) \cdot P(\omega_i)}{\sum P(\underline{x} / \omega_j) \cdot P(\omega_j)}$$

Decide  $\omega_i$  if  $P(\omega_i / \underline{x}) > P(\omega_j / \underline{x})$  for all  $i \neq j$

or

- Minimize the overall risk by selecting the action  $\alpha_i = \alpha_* : \text{deciding } \omega_2$

$$\alpha_* = \arg \min R(\alpha_i / \underline{x})$$

## Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem)

Here, we consider a 2-category problem in which the components of the feature vector are binary-valued and *conditionally independent* (which yields a simplified decision rule):

$$x = (x_1, \dots, x_d)^t, x_i \in \{0, 1\}$$

We also assign the following probabilities ( $p$  and  $q$ ) to each  $x_i$  in  $\mathbf{X}$ :

$$p_i = \Pr[x_i = 1 | \omega_1] \text{ and } q_i = \Pr[x_i = 1 | \omega_2]$$

## Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem)

If  $p_i > q_i$ , we expect to  $x_i$  to be 1 more frequently when the state of nature is  $w_1$  than when it is  $w_2$ . If we assume *conditional independence*, we can write  $P(\mathbf{X}|w_i)$  as the product of probabilities for the components of  $\mathbf{X}$ . The class conditional probabilities are then:

$$P(\mathbf{x}|\omega_1) = \prod_{i=1}^d p_i^{x_i} (1 - p_i)^{1-x_i}$$

$$P(\mathbf{x}|\omega_2) = \prod_{i=1}^d q_i^{x_i} (1 - q_i)^{1-x_i}$$

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem)

Since this is a two class problem the discriminant function  $g(\mathbf{x}) = g_1(\mathbf{x}) - g_2(\mathbf{x})$  where:

$$g_1(x) = \log [p(\mathbf{x}|\omega_1)p(\omega_1)] \text{ and } g_2(x) = \log [p(\mathbf{x}|\omega_2)p(\omega_2)]$$

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem)

The likelihood ratio is therefore given by:

$$\frac{P(\mathbf{x}|\omega_1)}{P(\mathbf{x}|\omega_2)} = \prod_{i=1}^d \left( \frac{p_i}{q_i} \right)^{x_i} \left( \frac{1-p_i}{1-q_i} \right)^{1-x_i}$$

which yields the discriminant function as follows:

$$g(x) = \ln \frac{P(\mathbf{x}|\omega_1)}{P(\mathbf{x}|\omega_2)} + \ln \frac{P(\omega_1)}{P(\omega_2)} = \sum_{i=1}^d \left[ x_i \ln \frac{p_i}{q_i} + (1-x_i) \ln \frac{1-p_i}{1-q_i} \right] + \ln \frac{P(\omega_1)}{P(\omega_2)}$$

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem)

If we notice that this function is linear in  $x_i$ , we can rewrite it as a linear function of  $x_i$

$$g(x) = \sum_{i=1}^d w_i x_i + w_0$$

where

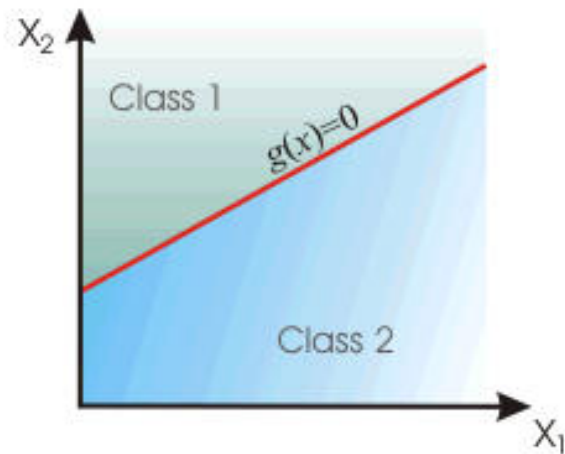
$$w_i = \ln \frac{p_i(1 - q_i)}{q_i(1 - p_i)}, i = 1, \dots, d$$

and

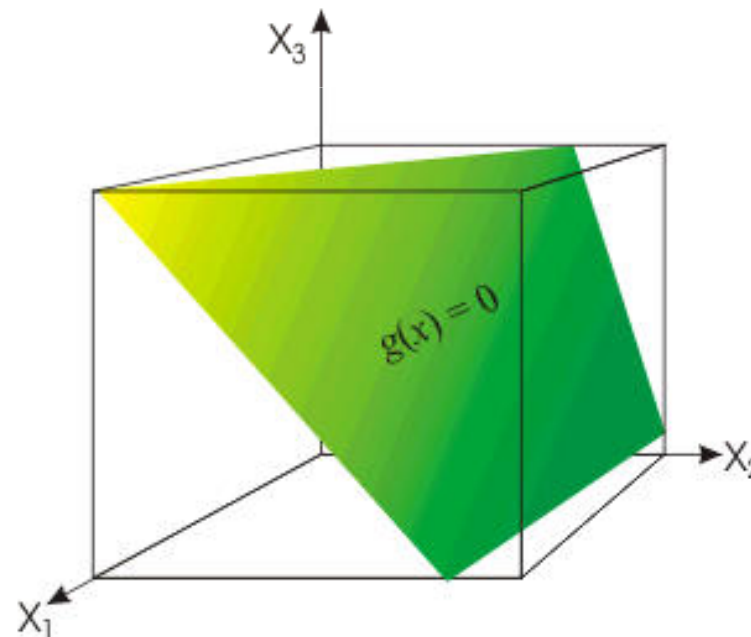
$$w_0 = \sum_{i=1}^d \ln \frac{1 - p_i}{1 - q_i} + \ln \frac{P(\omega_1)}{P(\omega_2)}$$

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem)

The discriminant function  $g(x)$  will therefore indicate whether the current feature vector belongs to class 1 and class 2. It is important to note that  $w_0$  and  $w_i$  are weights calculated for the linear discriminant. A decision boundary lies wherever  $g(x) = 0$ . This decision boundary can be a line, or hyper-plane depending upon the dimension of the feature space.



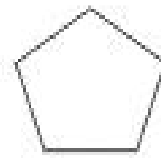
The decision boundary  $g(x) = 0$  is a line on a cartesian plan for a two dimensional ( $d = 2$ ) feature space.



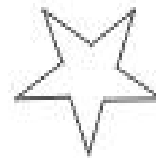
In a three dimensional feature space, the decision boundary  $g(x) = 0$  is a plane,

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem) EXAMPLE

Let's consider a three dimensional binary feature vector  $X=(x_1, x_2, x_3) = (0, 1, 1)$  that we will attempt to classify with one of the following classes:



Class 1



Class2

and let's say that the prior probability for class 1 is  $P(\omega_1) = 0.6$  while for class 2 is  $P(\omega_2) = 0.4$ . Hence, it is already evident that there is a bias towards class 1.

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem) EXAMPLE

Additionally, we know that likelihoods of each independent feature is given by  $p$  and  $q$  where:

$$p_i = P(x_i=1|\omega_1) \text{ and } q_i = P(x_i=1|\omega_2)$$

meaning that we know the probability (or likelihood) of each independent feature given each class - these values are known and given:

$$p = \{0.8, 0.2, 0.5\} \text{ and } q = \{0.2, 0.5, 0.9\}$$

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem) EXAMPLE

therefore, the discriminant function is  $g(\mathbf{x}) = g_1(\mathbf{x}) - g_2(\mathbf{x})$  or by taking the log of both sides:

$$g(x) = \log \frac{p(\mathbf{X}|\omega_1)}{p(\mathbf{X}|\omega_2)} + \log \frac{p(\omega_1)}{p(\omega_2)}$$

however, since the problem definition assumes that  $\mathbf{X}$  is independent, the discriminant function can be calculated by:

$$g(x) = \sum_{i=1}^d w_i x_i + w_o$$

with

$$w_i(x) = \ln \frac{p_i(1 - q_i)}{q_i(1 - p_i)} \quad i = 1, \dots, d$$

## Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem) EXAMPLE

$$w_i(x) = \ln \frac{p_i(1 - q_i)}{q_i(1 - p_i)} \quad i = 1, \dots, d$$

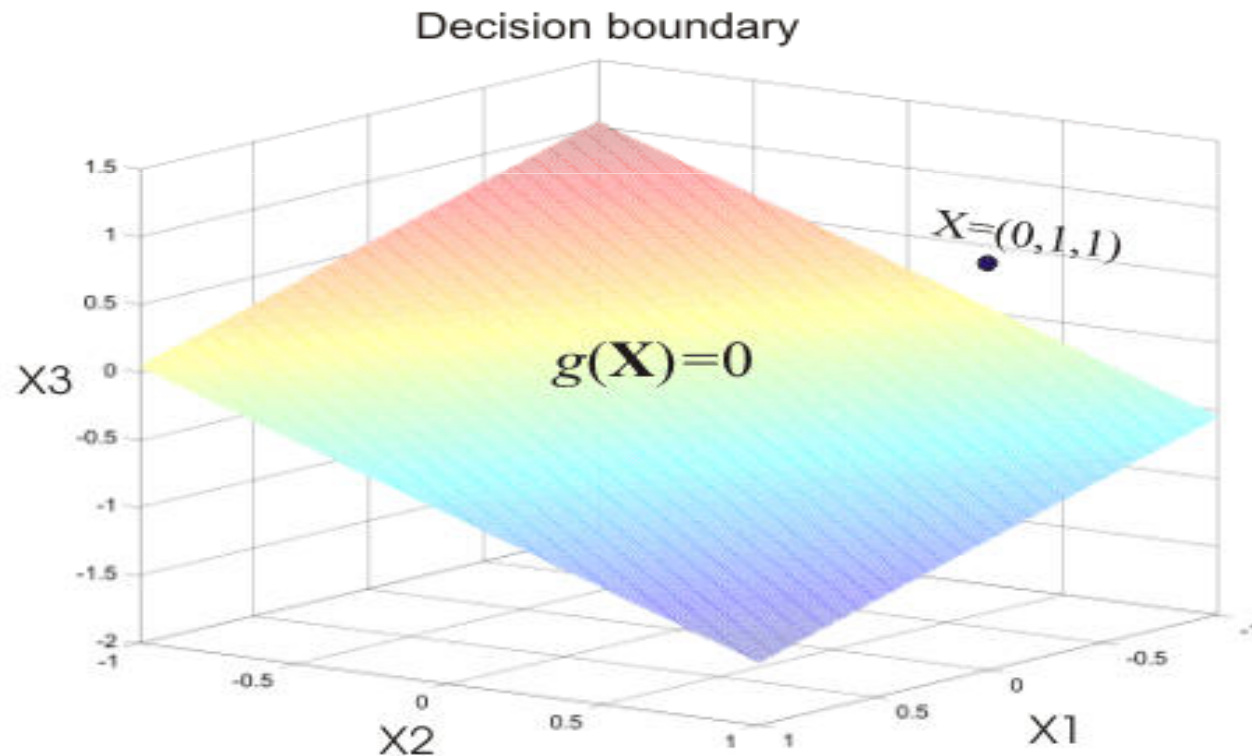
$$w_1 = \ln \frac{0.8(1-0.2)}{0.2(1-0.8)} = 2.77; w_2 = \ln \frac{0.2(1-0.5)}{0.5(1-0.2)} = -1.39; w_3 = \ln \frac{0.5(1-0.9)}{0.9(1-0.5)} = -2.19$$

$$w_0 = \ln \left( \frac{0.6}{0.4} \right) + \ln \left( \frac{1 - 0.8}{1 - 0.2} \right) + \ln \left( \frac{1 - 0.2}{1 - 0.5} \right) + \ln \left( \frac{1 - 0.5}{1 - 0.9} \right) = 1.0986$$

$$g(x) = 2.77x_1 - 1.39x_2 - 2.19x_3 + 1.0986$$

# Bayes Decision Theory – Discrete Features (Independent binary features in 2-category problem) EXAMPLE

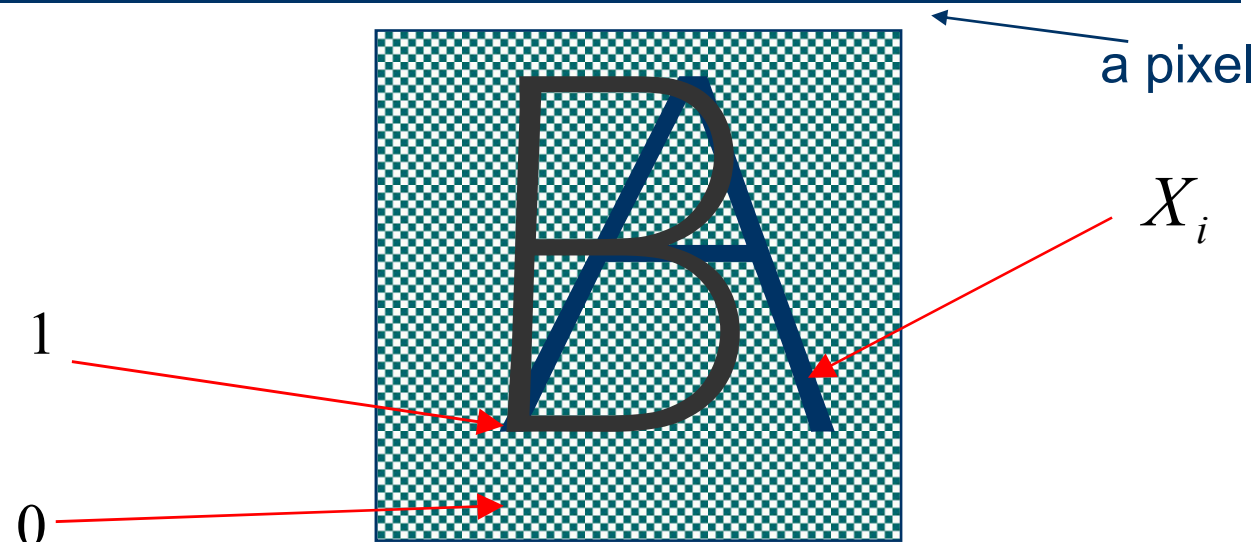
After inputting the  $x_i$  values into the discriminant function, the answer  $g(\mathbf{x}) = -2.4849$ . Therefore this belongs to class 2. Below is a plot of the decision boundary surface.



All points above the plane belong to class  $\omega_2$  since if  $\mathbf{X} = (0,1,1)$ ,  $g(\mathbf{x}) = -2.4849 < 0$ .

# APPLICATION EXAMPLE

Bit – matrix for machine – printed characters



Here, each pixel may be taken as a feature  $X_i$   $d = 10 \times 10 = 100$

For above problem, we have

$p_i$  is the probability that  $X_i = 1$  for letter A, B, ...

## Summary

- To minimize the overall risk, choose the action that minimizes the conditional risk  $\mathbf{R}(\alpha | \mathbf{x})$ .
- To minimize the probability of error, choose the class that maximizes the posterior probability  $\mathbf{P}(\mathbf{w}_j | \mathbf{x})$ .
- If there are different penalties for misclassifying patterns from different classes, the posteriors must be weighted according to such penalties before taking action.
- Do not forget that these decisions are the optimal ones under the assumption that the “true” values of the probabilities are known.